

**SECTION 23 0923**  
**DIRECT-DIGITAL CONTROL SYSTEM FOR HVAC**

**PART 1 GENERAL****1.1 SECTION INCLUDES**

- A. System description.
- B. Controllers.
- C. Power supplies and line filtering.
- D. System software.
- E. Controller software.
- F. HVAC control programs.

**1.2 RELATED REQUIREMENTS**

- A. Section 23 0993 - Sequence of Operations for HVAC Controls.
- B. Section 26 0583 - Wiring Connections: Electrical characteristics and wiring connections.

**1.3 REFERENCE STANDARDS**

- A. MIL-STD-810 - Environmental Engineering Considerations and Laboratory Tests; Revision G, 2014.
- B. NFPA 70 - National Electrical Code; Most Recent Edition Adopted by Authority Having Jurisdiction, Including All Applicable Amendments and Supplements.
- C. UL (DIR) - Online Certifications Directory; current listings at database.ul.com.

**1.4 SUBMITTALS**

- A. Product Data: Provide data for each system component and software module.
- B. Shop Drawings:
  - 1. Indicate trunk cable schematic showing programmable control unit locations, and trunk data conductors.
  - 2. Indicate system graphics indicating monitored systems, data (connected and calculated) point addresses, and operator notations. Provide demonstration diskette containing graphics.
  - 3. Show system configuration with peripheral devices, batteries, power supplies, diagrams, modems, and interconnections.
  - 4. Indicate description and sequence of operation of operating, user, and application software.
- C. Project Record Documents: Record actual locations of control components, including control units, thermostats, and sensors.
- D. Operation and Maintenance Data:
  - 1. Include interconnection wiring diagrams complete field installed systems with identified and numbered, system components and devices.
  - 2. Include keyboard illustrations and step-by-step procedures indexed for each operator function.
  - 3. Include inspection period, cleaning methods, cleaning materials recommended, and calibration tolerances.

**1.5 QUALITY ASSURANCE**

- A. Perform work in accordance with NFPA 70.
- B. Designer Qualifications: Perform design of system software under direct supervision of a Professional Engineer experienced in design of this type of work and licensed in Texas.

- C. Manufacturer Qualifications: Company specializing in manufacturing products specified in this section with minimum three years of documented experience.
- D. Installer Qualifications: Company specializing in performing work of the type specified and with minimum three years of documented experience.
- E. Products Requiring Electrical Connection: Listed and classified by UL (DIR) as suitable for purpose specified and indicated.

## PART 2 PRODUCTS

### 2.1 MANUFACTURERS

- A. Siemens AG, Building Technologies Division: [www.siemens.com](http://www.siemens.com).

### 2.2 SYSTEM DESCRIPTION

- A. Automatic temperature control field monitoring and control system using field programmable micro-processor based units.
- B. Base system on distributed system of fully intelligent, stand-alone controllers, operating in a multi-tasking, multi-user environment on token passing network, with central and remote hardware, software, and interconnecting wire and conduit.
- C. Include computer software and hardware, operator input/output devices, control units, local area networks (LAN), sensors, control devices, actuators.
- D. **Provide control systems consisting of connecting to BacNET controllers on DX split systems and roof top units. The points from the BACnet interface devices shall be mapped and displayed on graphics with the ability to trend the data. The system will report to the Rice University Campus System.**
- E. Include installation and calibration, supervision, adjustments, and fine tuning necessary for complete and fully operational system.

### 2.3 CONTROLLERS

#### A. BUILDING CONTROLLERS

- 1. General:
  - a. Manage global strategies by one or more, independent, standalone, microprocessor based controllers.
  - b. Provide sufficient memory to support controller's operating system, database, and programming requirements.
  - c. Share data between networked controllers.
  - d. Controller operating system manages input and output communication signals allowing distributed controllers to share real and virtual object information and allowing for central monitoring and alarms.
  - e. Utilize real-time clock for scheduling.
  - f. Continuously check processor status and memory circuits for abnormal operation.
  - g. Controller to assume predetermined failure mode and generate alarm notification upon detection of abnormal operation.
  - h. Communication with other network devices to be based on assigned protocol.
- 2. Communication:
  - a. Controller to reside on a BACnet network using ISO 8802-3 (ETHERNET) Data Link/Physical layer protocol.
  - b. Perform routing when connected to a network of custom application and application specific controllers.
  - c. Provide service communication port for connection to a portable operator's terminal or hand held device with compatible protocol.
- 3. Anticipated Environmental Ambient Conditions:

- a. Outdoors and/or in Wet Ambient Conditions:
    - 1) Mount within waterproof enclosures.
    - 2) Rated for operation at 40 to 150 degrees F.
  - b. Conditioned Space:
    - 1) Mount within dustproof enclosures.
    - 2) Rated for operation at 32 to 120 degrees F.
  4. Provisions for Serviceability:
    - a. Diagnostic LEDs for power, communication, and processor.
    - b. Make all wiring connections to field removable, modular terminal strips, or to a termination card connected by a ribbon cable.
  5. Memory: In the event of a power loss, maintain all BIOS and programming information for a minimum of 72 hours.
  6. Power and Noise Immunity:
    - a. Maintain operation at 90 to 110 percent of nominal voltage rating.
    - b. Perform orderly shutdown below 80 percent of nominal voltage.
    - c. Operation protected against electrical noise of 5 to 120 Hz and from keyed radios up to 5 W. at 3 feet.
- B. CUSTOM APPLICATION CONTROLLERS**
1. General:
    - a. Provide sufficient memory to support controller's operating system, database, and programming requirements.
    - b. Share data between networked, microprocessor based controllers.
    - c. Controller operating system manages input and output communication signals allowing distributed controllers to share real and virtual object information and allowing for central monitoring and alarms.
    - d. Utilize real-time clock for scheduling.
    - e. Continuously check processor status and memory circuits for abnormal operation.
    - f. Controller to assume predetermined failure mode and generate alarm notification upon detection of abnormal operation.
    - g. Communication with other network devices to be based on assigned protocol.
  2. Communication:
    - a. Controller to reside on a BACnet network using MS/TP Data Link/Physical layer protocol.
    - b. Provide service communication port for connection to a portable operator's terminal or hand held device with compatible protocol.
  3. Anticipated Environmental Ambient Conditions:
    - a. Outdoors and/or in Wet Ambient Conditions:
      - 1) Mount within waterproof enclosures.
      - 2) Rated for operation at 40 to 150 degrees F.
    - b. Conditioned Space:
      - 1) Mount within dustproof enclosures.
      - 2) Rated for operation at 32 to 120 degrees F.
  4. Provisions for Serviceability:
    - a. Diagnostic LED's for power, communication, and processor.
    - b. Make all wiring connections to field removable, modular terminal strips, or to a termination card connected by a ribbon cable.
  5. Memory: In the event of a power loss, maintain all BIOS and programming information for a minimum of 72 hours.
  6. Power and Noise Immunity:
    - a. Maintain operation at 90 to 110 percent of nominal voltage rating.
    - b. Perform orderly shutdown below 80 percent of nominal voltage.

- c. Operation protected against electrical noise of 5 to 120 Hz and from keyed radios up to 5 W. at 3 feet.

#### C. INPUT/OUTPUT INTERFACE

1. Hardwired inputs and outputs tie into the DDC system through building, custom application, or application specific controllers.
2. All Input/Output Points:
  - a. Protect controller from damage resulting from any point short-circuiting or grounding and from voltage up to 24 volts of any duration.
  - b. Provide universal type for building and custom application controllers where input or output is software designated as either binary or analog type with appropriate properties.
3. Binary Inputs:
  - a. Allow monitoring of On/Off signals from remote devices.
  - b. Provide wetting current of 12 mA minimum, compatible with commonly available control devices and protected against the effects of contact bounce and noise.
  - c. Sense dry contact closure with power provided only by the controller.
4. Pulse Accumulation Input Objects: Conform to all requirements of binary input objects and accept up to 10 pulses per second.
5. Analog Inputs:
  - a. Allow for monitoring of low voltage 0 to 10 VDC, 4 to 20 mA current, or resistance signals (thermistor, RTD).
  - b. Compatible with and field configurable to commonly available sensing devices.
6. Binary Outputs:
  - a. Used for On/Off operation or a pulsed low-voltage signal for pulse width modulation control.
  - b. Outputs provided with three position (On/Off/Auto) override switches.
  - c. Status lights for building and custom application controllers to be selectable for normally open or normally closed operation.
7. Analog Outputs:
  - a. Monitoring signal provides a 0 to 10 VDC or a 4 to 20 mA output signal for end device control.
  - b. Provide status lights and two position (AUTO/MANUAL) switch for building and custom application controllers with manually adjustable potentiometer for manual override on building and custom application controllers.
  - c. Drift to not exceed 0.4 percent of range per year.
8. Tri State Outputs:
  - a. Coordinate two binary outputs to control three point, floating type, electronic actuators without feedback.
  - b. Limit the use of three point, floating devices to the following zone and terminal unit control applications:
  - c. Control algorithms run the zone actuator to one end of its stroke once every 24 hours for verification of operator tracking.
9. System Object Capacity:
  - a. System size to be expandable to twice the number of input output objects required by providing additional controllers, including associated devices and wiring.
  - b. Hardware additions or software revisions for the installed operator interfaces are not to be required for future, system expansions.

## 2.4 POWER SUPPLIES AND LINE FILTERING

- A. Power Supplies:

1. Provide UL listed control transformers with Class 2 current limiting type or over-current protection in both primary and secondary circuits for Class 2 service as required by the NEC.
  2. Limit connected loads to 80 percent of rated capacity.
  3. Match DC power supply to current output and voltage requirements.
  4. Unit to be full wave rectifier type with output ripple of 5.0 mV maximum peak to peak.
  5. Regulation to be 1 percent combined line and load with 100 microsecond response time for 50 percent load changes.
  6. Provide over-voltage and over-current protection to withstand a 150 percent current overload for 3 seconds minimum without trip-out or failure.
  7. Operational Ambient Conditions: 32 to 120 degrees F.
  8. EM/RF meets FCC Class B and VDE 0871 for Class B and MIL-STD 810 for shock and vibration.
  9. Line voltage units UL recognized and CSA approved.
- B. Power Line Filtering:
1. Provide external or internal transient voltage and surge suppression component for all workstations and controllers.
  2. Minimum surge protection attributes:
    - a. Dielectric strength of 1000 volts minimum.
    - b. Response time of 10 nanoseconds or less.
    - c. Transverse mode noise attenuation of 65 dB or greater.
    - d. Common mode noise attenuation of 150 dB or greater at 40 to 100 Hz.

## 2.5 LOCAL AREA NETWORK (LAN)

- A. Provide communication between control units over local area network (LAN).
- B. LAN Capacity: Not less than 60 stations or nodes.
- C. Break in Communication Path: Alarm and automatically initiate LAN reconfiguration.
- D. LAN Data Speed: Minimum 19.2 Kb.
- E. Communication Techniques: Allow interface into network by multiple operation stations and by auto-answer/auto-dial modems. Support communication over telephone lines utilizing modems.
- F. Transmission Median: Fiber optic or single pair of solid 24 gage twisted, shielded copper cable.
- G. Network Support: Time for global point to be received by any station, shall be less than 3 seconds. Provide automatic reconfiguration if any station is added or lost. If transmission cable is cut, reconfigure two sections with no disruption to system's operation, without operator intervention.

## 2.6 SYSTEM SOFTWARE

- A. Operating System: Compatible with existing Siemens Control System
  1. Concurrent, multi-tasking capability.
    - a. Common Software Applications Supported: Microsoft Excel.
  2. System Graphics:
    - a. Allow up to 10 graphic screens, simultaneously displayed for comparison and monitoring of system status.
    - b. Animation displayed by shifting image files based on object status.
    - c. Provide method for operator with password to perform the following:
      - 1) Move between, change size, and change location of graphic displays.
      - 2) Modify on-line.
      - 3) Add, delete, or change dynamic objects consisting of:
        - (a) Analog and binary values.
        - (b) Dynamic text.

- (c) Static text.
  - (d) Animation files.
- 3. Custom Graphics Generation Package:
  - a. Create, modify, and save graphic files and visio format graphics in PCX formats.
  - b. HTML graphics to support web browser compatible formats.
  - c. Capture or convert graphics from AutoCAD.
- 4. Standard HVAC Graphics Library:
  - a. HVAC Equipment:
    - 1) Chillers.
    - 2) Boilers.
    - 3) Air Handlers.
    - 4) Terminal HVAC Units.
    - 5) Fan Coil Units.
  - b. Ancillary Equipment:
    - 1) Fans.
    - 2) Pumps.
    - 3) Coils.
    - 4) Valves.
    - 5) Piping.
    - 6) Dampers.
    - 7) Ductwork.

## 2.7 CONTROLLER SOFTWARE

- A. All applications reside and operate in the system controllers and editing of all applications occurs at the operator workstation.
- B. System Security:
  - 1. User access secured via user passwords and user names.
  - 2. Passwords restrict user to the objects, applications, and system functions as assigned by the system manager.
  - 3. User Log On/Log Off attempts are recorded.
  - 4. Automatic Log Off occurs following the last keystroke after a user defined delay time.
- C. Object or Object Group Scheduling:
  - 1. Weekly Schedules Based on Separate, Daily Schedules:
    - a. Include start, stop, optimal stop, and night economizer.
    - b. 10 events maximum per schedule.
    - c. Start/stop times adjustable for each group object.
- D. Provide standard application for equipment coordination and grouping based on function and location to be used for scheduling and other applications.
- E. Alarms:
  - 1. Binary object is set to alarm based on the operator specified state.
  - 2. Analog object to have high/low alarm limits.
  - 3. All alarming is capable of being automatically and manually disabled.
  - 4. Alarm Reporting:
    - a. Operator determines action to be taken for alarm event.
    - b. Alarms to be routed to appropriate workstation.
    - c. Reporting Options:
- F. Maintenance Management: System monitors equipment status and generates maintenance messages based upon user-designated run-time limits.
- G. Sequencing: Application software based upon specified sequences of operation in Section 23 0993.

- H. PID Control Characteristics:
  - 1. Direct or reverse action.
  - 2. Anti-windup.
  - 3. Calculated, time-varying, analog value, positions an output or stages a series of outputs.
  - 4. User selectable controlled variable, set-point, and PED gains.
- I. Staggered Start Application:
  - 1. Prevents all controlled equipment from simultaneously restarting after power outage.
  - 2. Order of equipment startup is user selectable.
- J. Energy Calculations:
  - 1. Accumulated instantaneous power or flow rates are converted to energy use data.
  - 2. Algorithm calculates a rolling average and allows window of time to be user specified in minute intervals.
  - 3. Algorithm calculates a fixed window average with a digital input signal from a utility meter defining the start of the window period that in turn synchronizes the fixed-window average with that used by the power company.
- K. Anti-Short Cycling:
  - 1. All binary output objects protected from short-cycling.
  - 2. Allows minimum on-time and off-time to be selected.
- L. On-Off Control with Differential:
  - 1. Algorithm allows binary output to be cycled based on a controlled variable and set-point.
  - 2. Algorithm to be direct-acting or reverse-acting incorporating an adjustable differential.
- M. Run-Time Totalization:
  - 1. Totalize run-times for all binary input objects.
  - 2. Provides operator with capability to assign high run-time alarm.

### **PART 3 EXECUTION**

#### **3.1 EXAMINATION**

- A. Verify existing conditions before starting work.

#### **3.2 INSTALLATION**

- A. Install control units and other hardware in position on permanent walls where not subject to excessive vibration.
- B. Install software in control units and in operator work station. Implement all features of programs to specified requirements and appropriate to sequence of operation. Refer to Section 23 0993.
- C. Provide conduit and electrical wiring in accordance with Section 26 0583. Electrical material and installation shall be in accordance with appropriate requirements of .

**END OF SECTION 23 0923**